



Easy-OBU

System requirements and properties of Easy-OBU

Praha, 23nd of January 2013, Dr. Hannes Stratil



Easy-OBU research project in a nutshell: GSA supported international project aimed at an introduction of cheap positioning solution with improved accuracy

- **What are we doing:** we are developing and preparing market introduction of a new On-Board-Unit capable of providing more accurate location information in challenging situations (such as tunnels) at low cost
- **Who we are:** an international consortium consisting of Efcon (AT), PWP Systems (DE), Austriatech (AT), ITS&S Association (CZ) and ČVUT (CZ)
- **Public support:** the project is partially funded from the 7th Frame Programme of the European Union

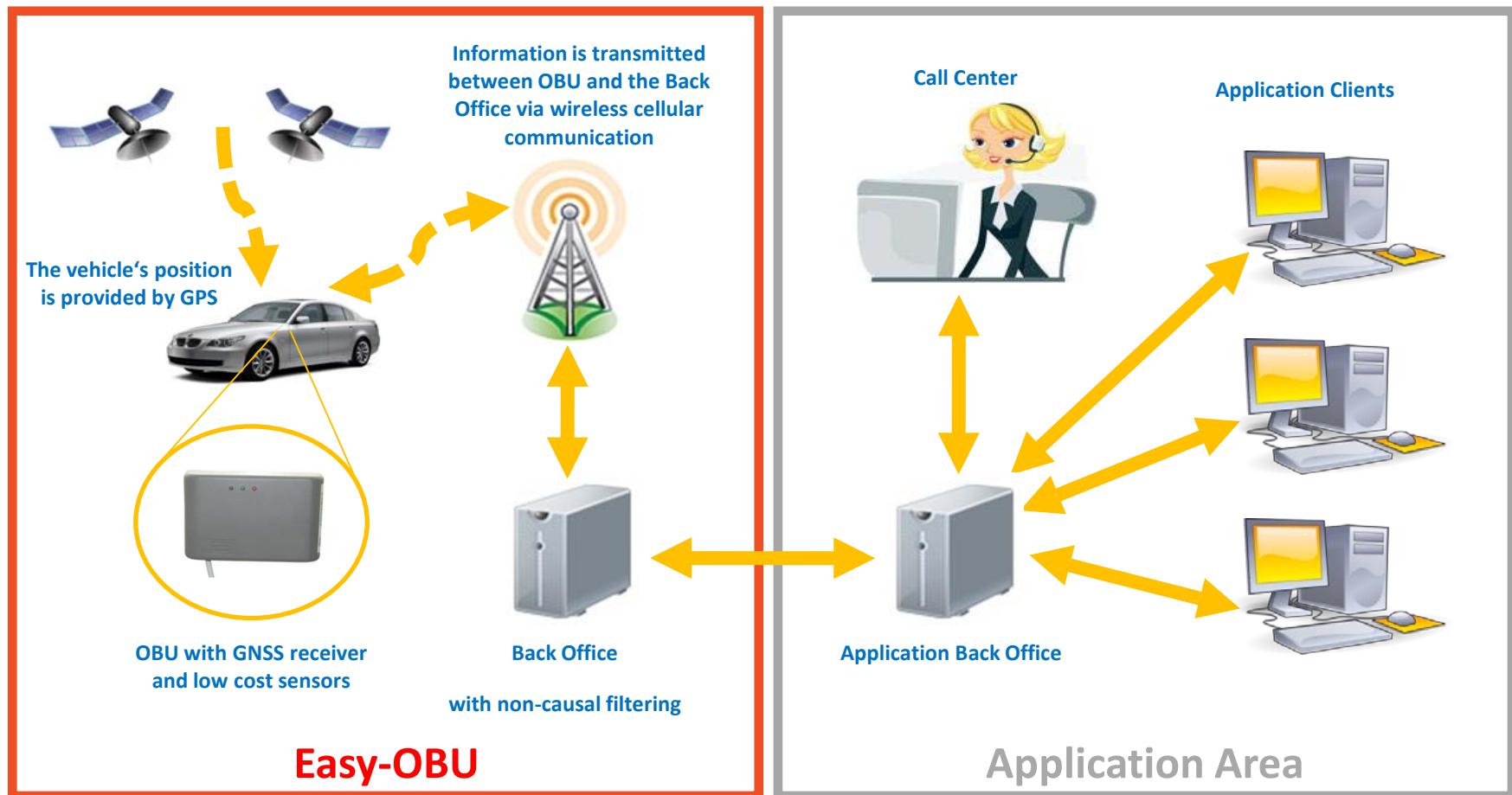


This project is funded by the European Union and carried out in the context
of the Galileo FP7 R&D programme supervised by the GSA

Easy-OBU - System requirements

- Easy-OBU should provide - at least - the same or better performance as existing simple GNSS based positioning systems.
- Easy-OBU should use simple and mass-market components and sensors (GNSS, Gyrometer, Accelerometer)
- OBU should be easy to install into the vehicle
- Easy-OBU should improve the availability of position information for situations where GNSS signals are not available.
- Easy-OBU should improve the accuracy of position information in situations of large positioning errors.
- Retrospective calculation of position information for challenging situations should be used

Easy-OBU project – System Architecture



Easy-OBU - System interfaces

- **Interface 1**

Open interface at the central server

Used by end-users to access the data

Data in the central server are application independent

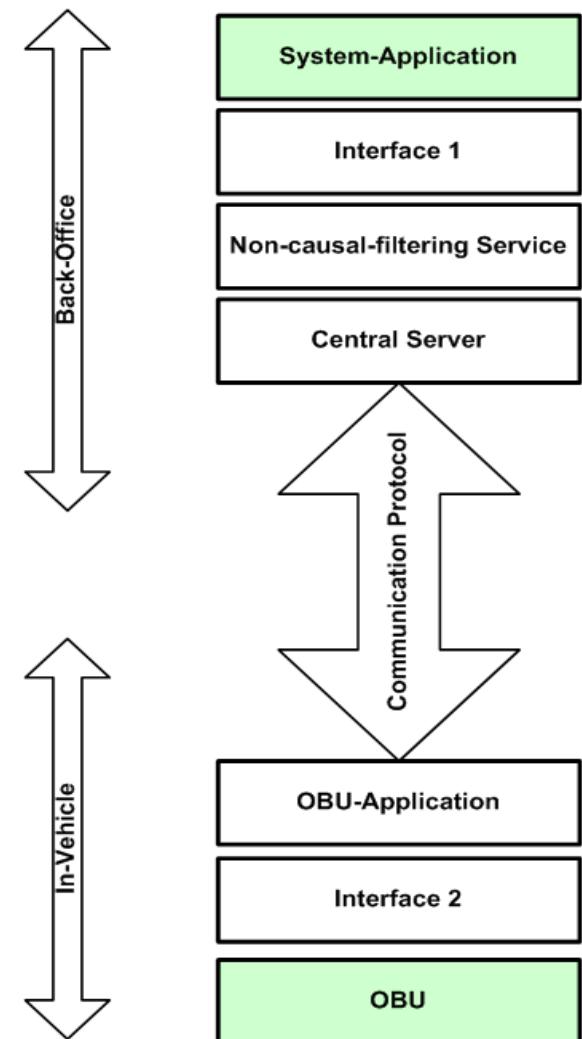
System application can run in another location

- **Interface 2**

Open interface inside of OBU

Specifies the sensor information required by Easy-OBUs

Used by OBU provides to integrate their own OBU into Easy-OBUs



Easy-OBU – provided properties

Performance parameter:

- Availability > 99.9 %
 - Position accuracy: < 10 m
 - Heading accuracy: < 5 °
 - Velocity accuracy: < 2 km/h
 - Accuracy of distance travelled < 1 %
 - Time accuracy: < 0.5 s
 - Position update rate: 1 Hz
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- **Light weight unit in the vehicle**
 - **Small in size (the view through the windscreen is not disturbed)**



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<http://www.sdt.cz/page.php?id=102>