

## WIM-E

# **Network of National ITS Associations Workshops**

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#### **Overloaded Heavy Vehicles**

## Damages to road network, bridges and pavement

## **Overloading contributes**

to serious

road safety problems





- less stable vehicle
- difficult to steer
- massive strain on vehicle tires
- insurance cover is void
- unfair on other operators
- more fuel consumption



#### **Our Solution**

# Weigh-in-Motion – Enforcement:

## doubtless identification with

digital image documentation

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## Weight-In-Motion (WIM) Systems



Dr. Thomas Spindler



## Main Purpose:

Identification and manual verification of over-loaded vehicles (WIM-S + camera and fast data transmission)



#### **Disadvantage:**

### Personnel and time consuming

- Very limited amount of trucks can be inspected
- •Inspections published >> drivers avoid these roads



## Weigh-In-Motion Enforcement (WIM-E)

#### Main Purpose:

Fully automated WIM system that weighs every passing vehicle, stores data of overloaded trucks and transmits data to enforcement authorities

## **Necessary Equipment:**

•WIM-E electronics
•Photo+video+ANPR camera, data storage and coding equipment
•Back office

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- •Permanent surveillance (24h / 7d)
- Near 100% acquisition of all overloaded trucks
- Prevent future incidents (learning process)
- •Number plate 'Black List' feature
- Increase lifetime (lower maint. costs etc.)

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- first WIM-E system in December 2007
- proof inadequate use of road (weight limit: 12t)
- ~500 events per month





### Weight-In-Motion - Enforcement



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#### **Camera System**





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## **Violation camera specifications**

CCD sensor:	Monochrome or color			
Scanning system:	Progressive scan			
Effective pixels:	11 M pixels			
AD converter:	14 bits / pixels			
Shutter:	Electronic shutter 1/50 to 1/10,000 s			
Lens connection:	ROBOT Mount			
System connections:	Sync, Trigger, RS422/232 IEEE-1394			
Temperature range:	-20° to +60°C, fan-less			



## Violation camera image (sample data)

Date	Time	Weight	Speed	Code	
15.08.2	006 17:24:36.015	11 t	85 km/h	76548	
SPeed	Time Date	Code	Photo L Int	Fix Site	TraffiStar
056 km	∕h 16:31:05 19.06.20	106	476 0 1	050	S540
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#### Sequence camera image



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#### **Coverage of OCR Algorithm**





- Weighing sensors installed in the road
- Forces penetrate sensors when wheels pass by
- Charges are generated through these forces
- Charges are amplified
- Analog signals are digitalized and processed
- Integration represent weight of wheel
- Results are class, weight, speed, length, gap

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- WIM Accuracy ok
- Photo Documentation ok

but

Court proven violations are required

- •Fixed tolerance
- Suppression of false events



### LINEAS<sup>®</sup> quartz sensor by Kistler





### Sensors, installation and Signals

1. Measurement



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2. Measurement



#### Advantages of the LINEAS® sensor

- Little damage to road surface
- Long term stability
- Sensor needs no servicing
- No drainage / no frame



- Almost invisible for drivers
- Independent of temperature changes

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- Independent of external forces
- Optimal surface adaption
- Entire road connection
- HS- and LS-WIM\*





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- Scanning rate: 4,000s/s/sensor (4/8 sensors per lane)
- 16 single or 8 double loops, self tuning
- Up to 6 WIM lanes (double sensor lines)
- Up to 10 vehicle classes, up to 63 axle classes
- Integral GSM/GPRS modem
- Plug-in SD card
- SIM card front-accessible
- Integral graphic display



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## **WIM system specifications**

- Error of measurement: < 5% (2 rows)
- Lifetime is dependent on quality of roads
- Data volume: ≈ 1 MByte/day/lane
- No temperature compensation necessary
- 32-bit processor
- RS 232/RS485 interfaces
- WLAN
- Power 12V to 24V



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#### **Collected data**

• Total weight

Wheel load

Axle load

Axle group

load

- Classification
- Speed
- Headway/Gap



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# Conclusion

WIM-P & WIM-E both improve traffic safety

**WIM-E** provides major benefits

- no traffic disturbance
- close to 100% coverage
- reduced man power
- short term amortization